

Computer Graphics

- Shadow Algorithms -

Philipp Slusallek

Recap: Shadows

- **Lightsource contributes to shading if the lightsource is visible from the sampling point**
- **Contributions of lightsources are added**

```
Color shade( Point surfacePosition, Direction toCamera )
{
    Color outgoing = black;
    for ( light : lightsources )
        if ( ! occluded( surfacePosition, light.position ) )
            {
                Color incoming = light.illuminate( surfacePosition );
                Direction toLight = light.position – surfacePoint;
                outgoing += brdf( incoming, toCamera, toLight );
            }
    return totalColor;
}
```

Recap: Visibility Queries

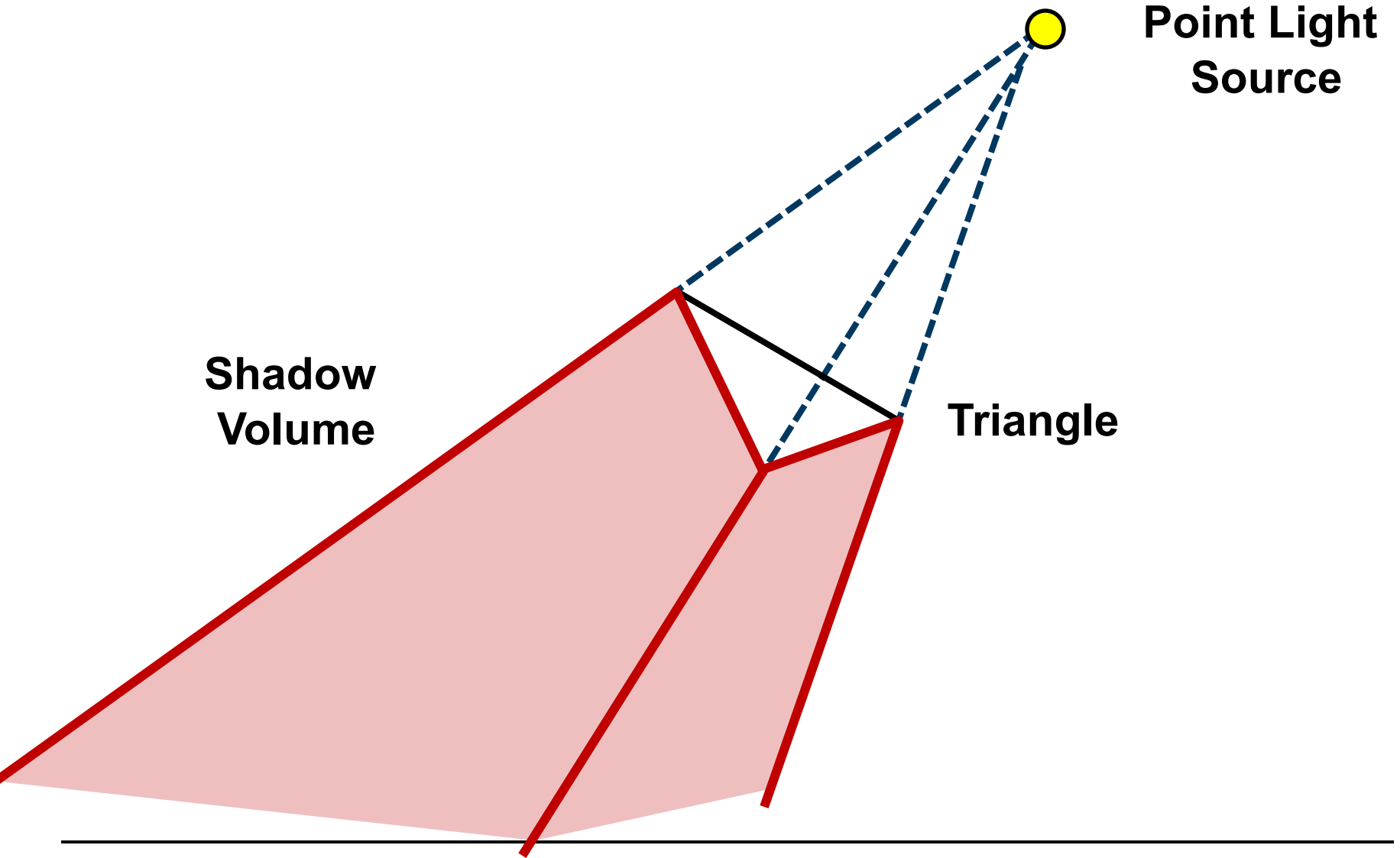
- **Visibility queries**
 - Simplified ray tracing operations
 - **Normal ray-scene intersection:**
 - Find first intersection with scene
 - **Visibility Query:**
 - Find any intersection with scene (slightly faster)
 - **Rasterization context**
 - Ray-scene intersection operation is not available
 - No access to other triangles from within the pipeline
-

Shadowing in Rasterization

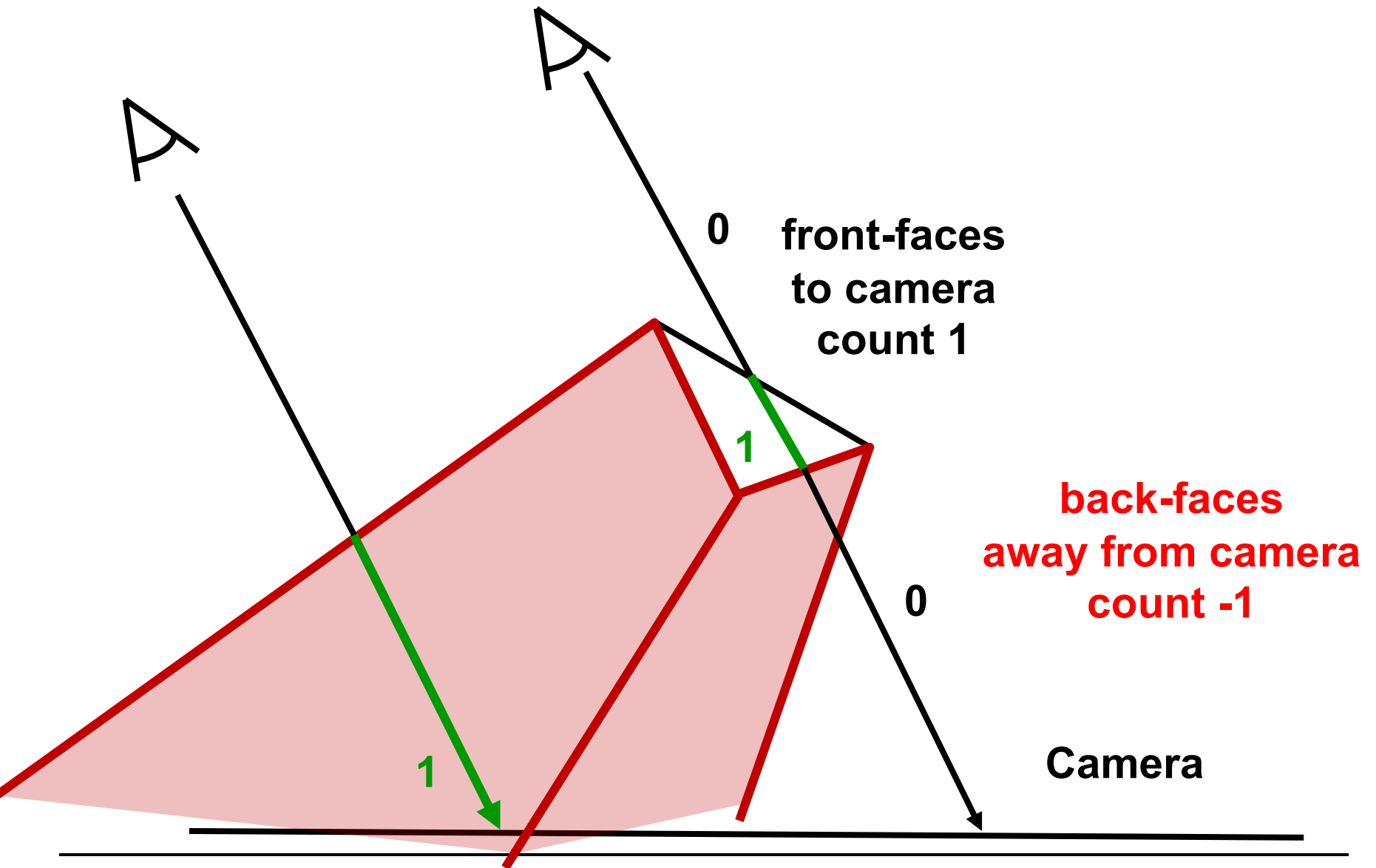
- **Direct (subtractive) shadow rendering (historic)**
 - Render scene without shadows
 - „Add“ shadows later by subtracting light (e.g. via geometry)
 - No consistent interpretation in terms of rendering equation
 - **Shadow Volumes (Hard Shadows)**
 - Precompute volume representation of light visibility
 - Use visibility information during rendering
 - **Shadow Maps (Hard Shadows)**
 - Precompute a discrete representation of light visibility
 - Use visibility information during rendering
 - **Hybrid Rendering Techniques (Soft Shadows)**
 - Use cone-tracing in a scene approximation
-

SHADOW VOLUMES

Shadow Volumes



Shadow Volumes



Shadow Volume Algorithm

1. fill z-buffer as seen from camera (disable writing to FB)
2. fill color buffer to black
3. for (light : lightsources)
 4. initialize stencil buffer to zero
 5. compute all front facing shadow volume surfaces
 6. render to stencil buffer with value 1
 7. compute all back facing shadow volume surfaces
 8. render stencil buffer with value -1
 9. render scene from camera only, adding illum where shadow volume buffer $\neq 0$

Properties

- **Pro**

- Per pixel accurate shadows without aliasing problems
- Maps moderat well to hardware

- **Con**

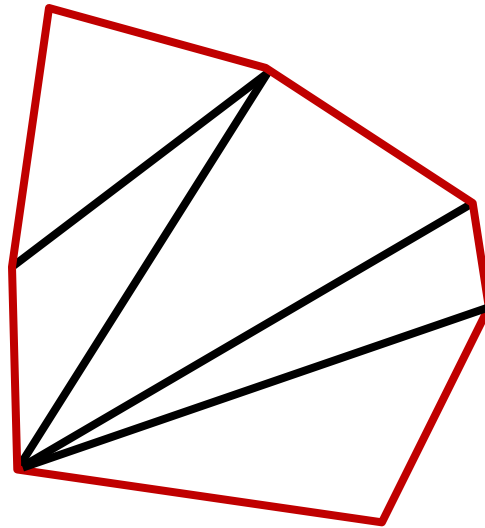
- Needs major changes to how scene is rendered

- **Performance**

- Generate 3 faces per triangle-light combination
- Poor performance for geometrically complex shadow casters
- Very bandwidth intensive

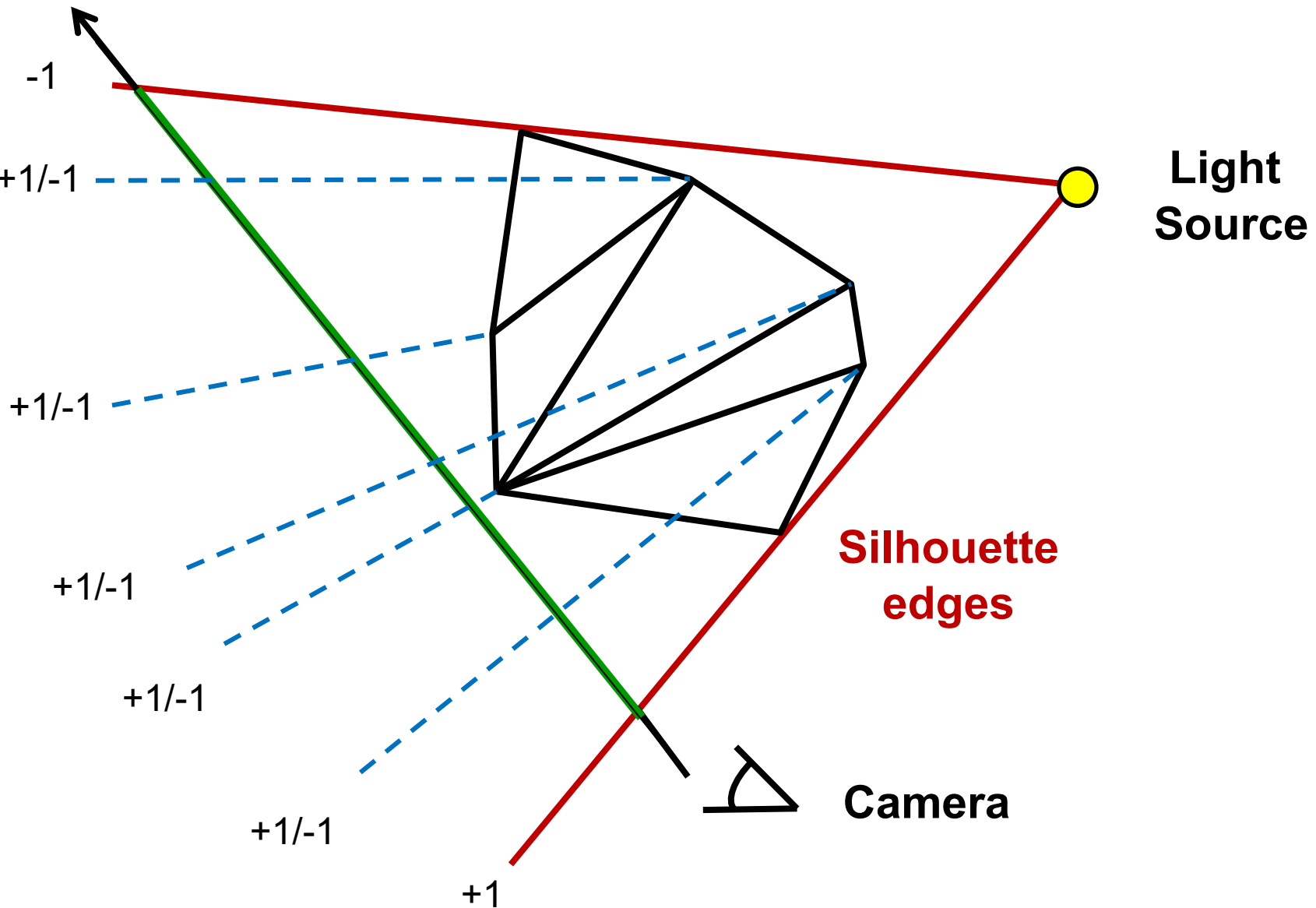
Optimization: Silhouettes

- Mesh as seen from light source
- Only silhouette edges are relevant



**silhouette
edges**

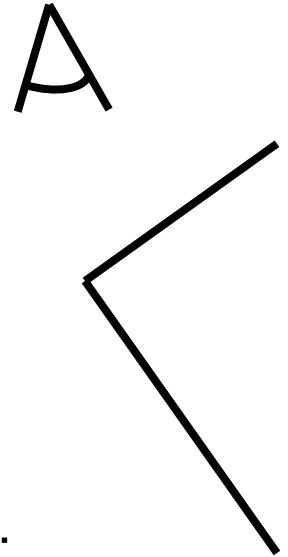
Optimization: Silhouettes



Finding silhouettes

- **Brute force approach (convex objects)**

```
for ( light: scene )
  for ( edge : mesh )
  {
    normal1 = edge.face1.normal;
    normal2 = edge.face2.normal;
    camera = directionToCamera;
    direction1 := sign( dotProduct(normal1, camera) );
    direction2 := sign( dotProduct(normal2, camera) );
    isSilhouette[light, edge] := (direction1 != direction2);
  }
```



- Finding general silhouettes is a difficult topic in itself
- Possible optimization
 - Edges between planer triangles can be disregarded

Further Reading

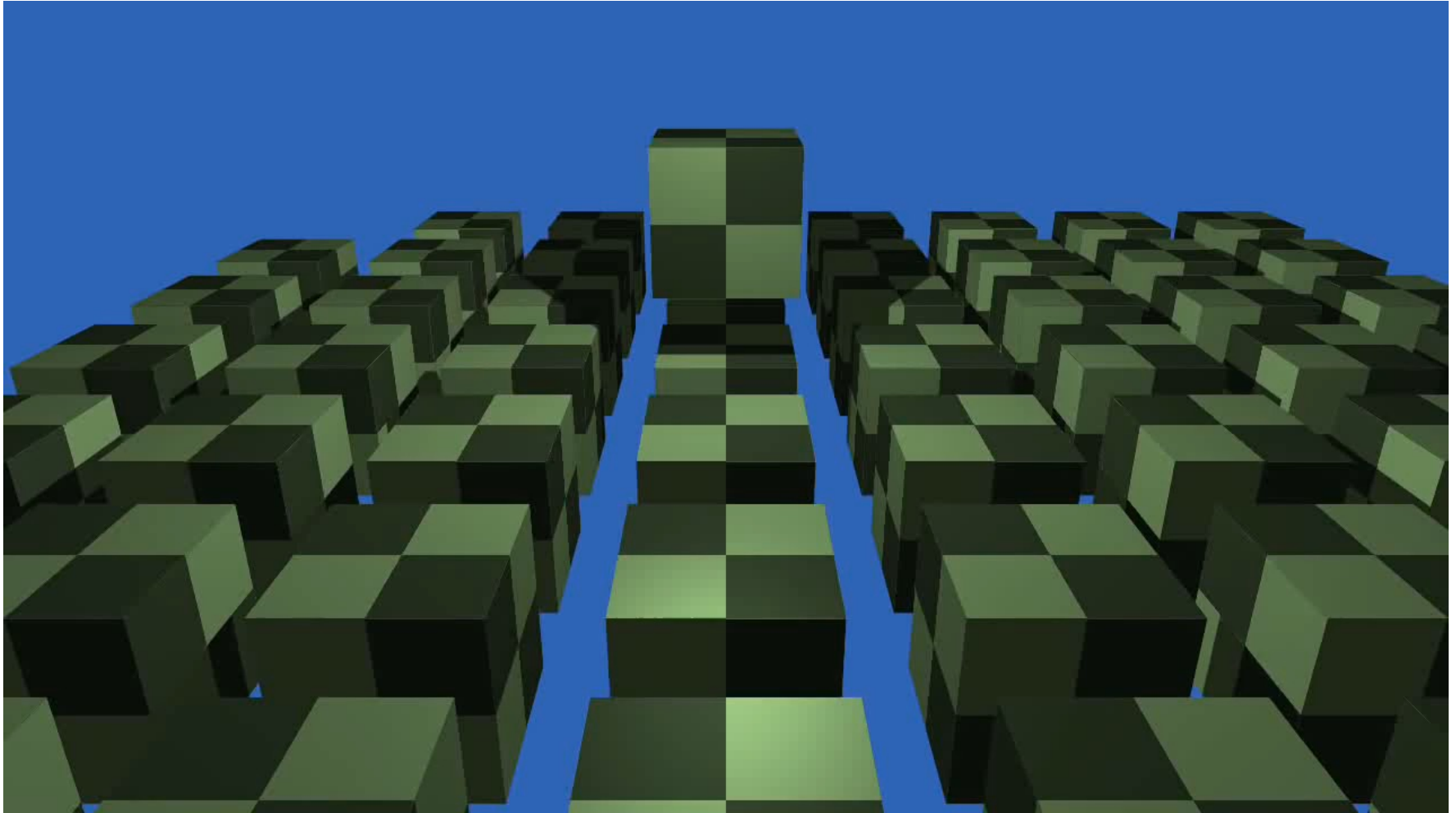
Approximate approach:

Markosian, Lee et. al. *Real-Time Nonphotorealistic Rendering*, Proceedings of SIGGRAPH 1997, pp. 415-420

Using Gauss Maps:

Gooch, Amy, et. al. „*A Non-Photorealistic Lighting Model for Automatic Technical Illustrations*“, Proceedings of SIGGRAPH 1998, pp. 447-452

Shadow Volumes Example



SHADOW MAPS

Shadow Mapping

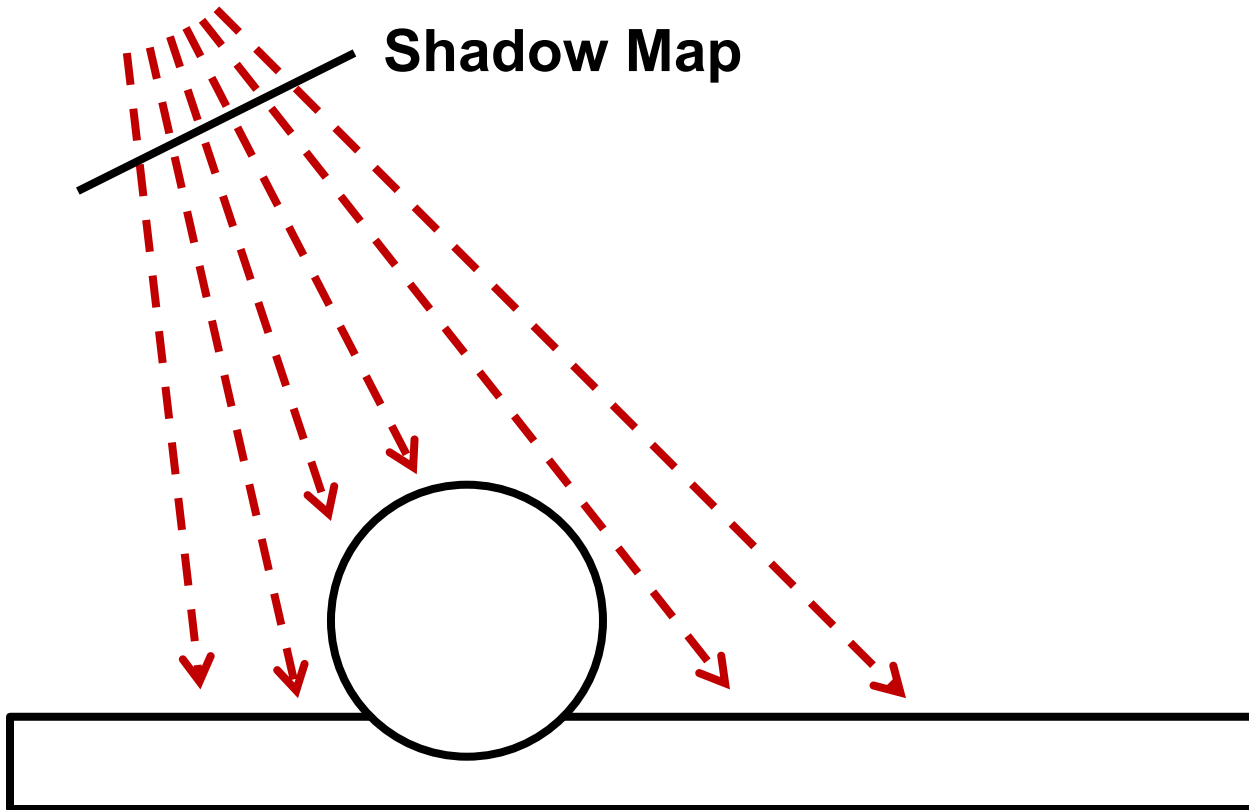
- **Idea: Use Z-Buffer to store occlusion information**
- **First pass: Render scene from position of light source**
 - For each pixel: Store distance from lightsource to object
 - Resulting data structure is called shadow map
- **Second pass: Render scene from position of camera**
 - For each pixel: Compare distance to lightsource with corresponding pixel in shadow map

Shadow Mapping

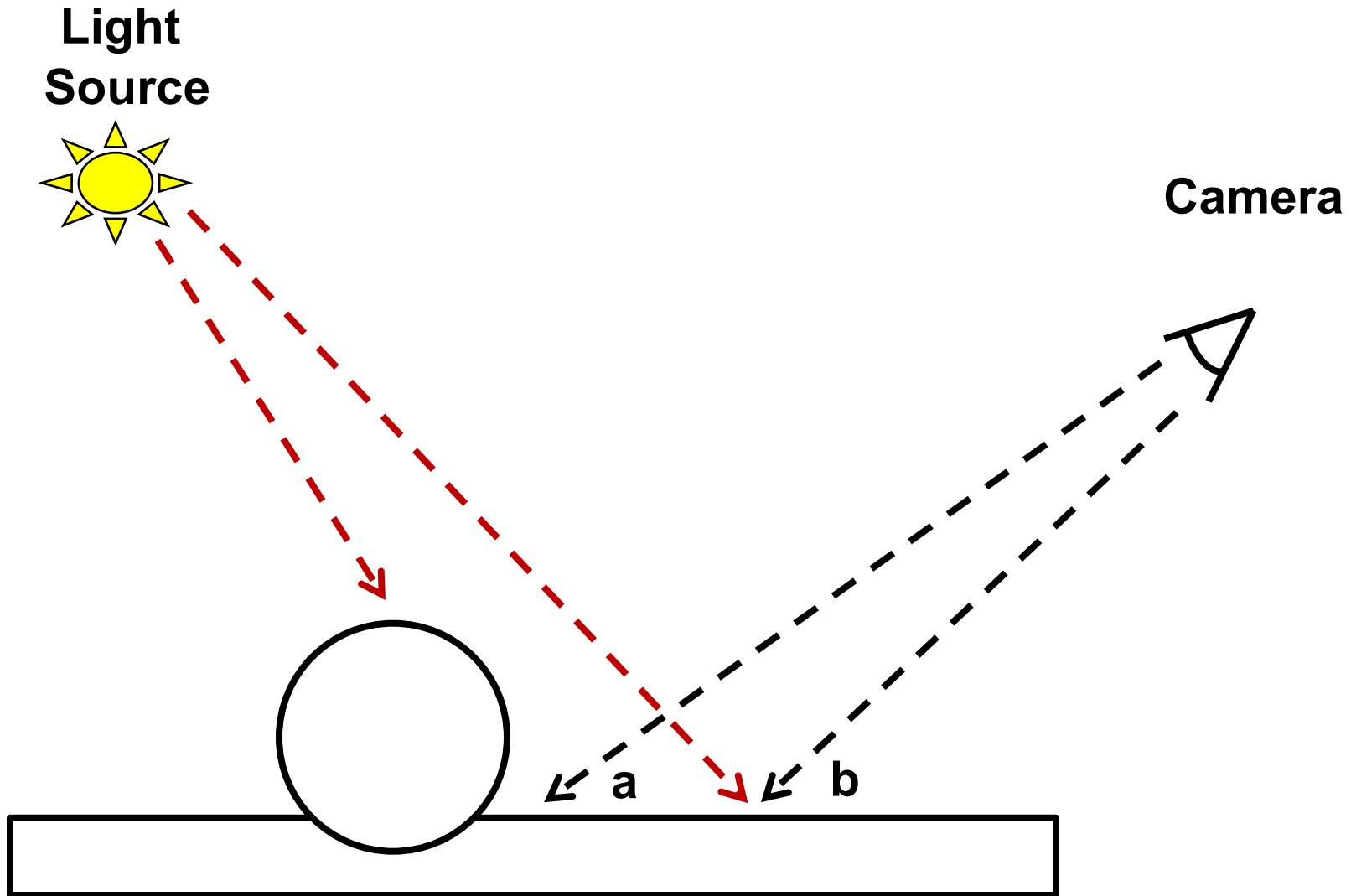
Light
Source



Shadow Map



Shadow Mapping



Properties

- **Pro**

- Very flexible: can handle arbitrary shadow casters
- Can handle semi-transparent shadow casters
- Maps well to hardware

- **Con**

- Aliasing problems occur as shadow map samples are in general not at same positions as camera samples
- Aliasing is a principal problem of shadow maps – can be reduced but not avoided
- Difficult question where to place the shadow map

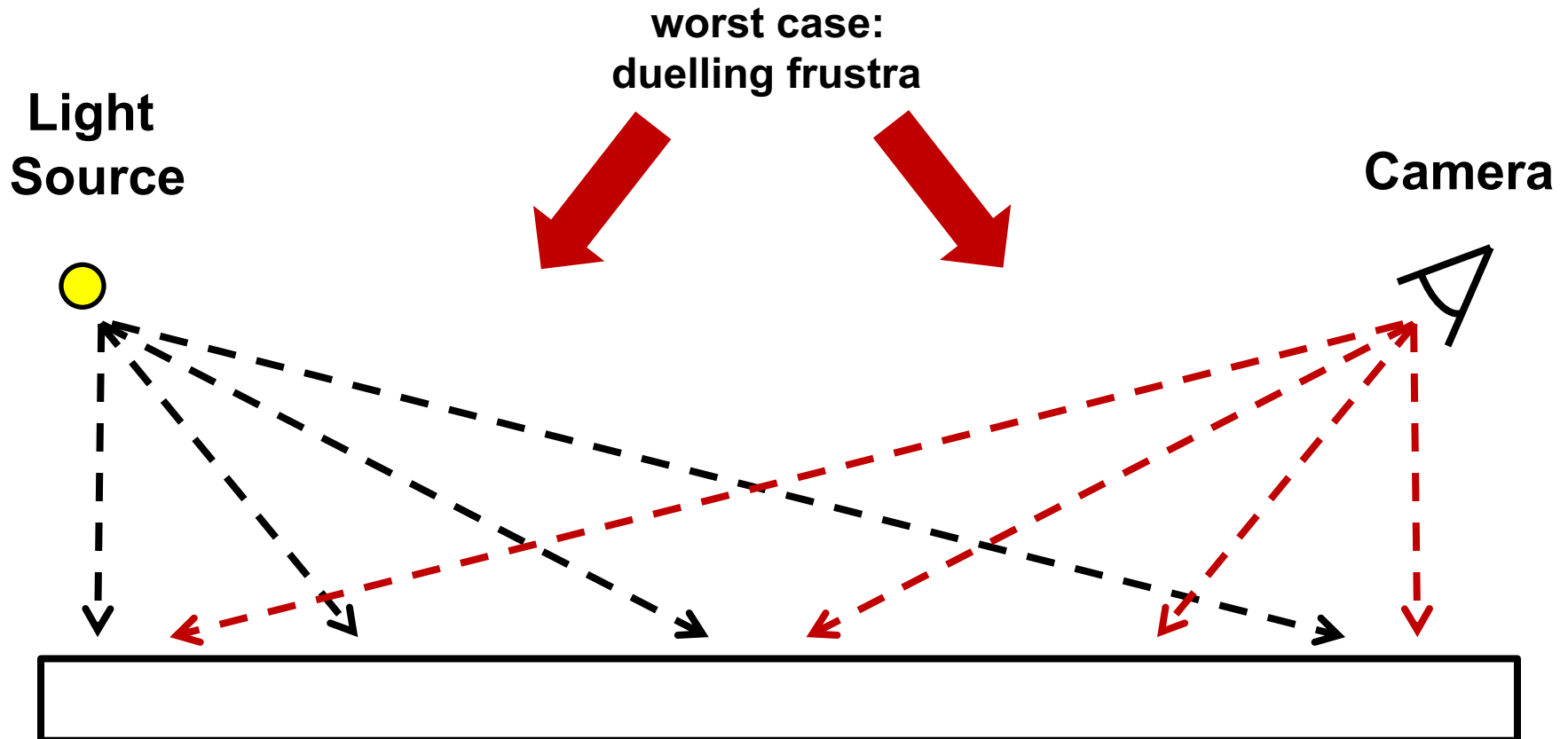
- **Performance**

- One additional render pass per light source
- Moderate memory consumption for shadow maps

Dueling Frustra and Aliasing

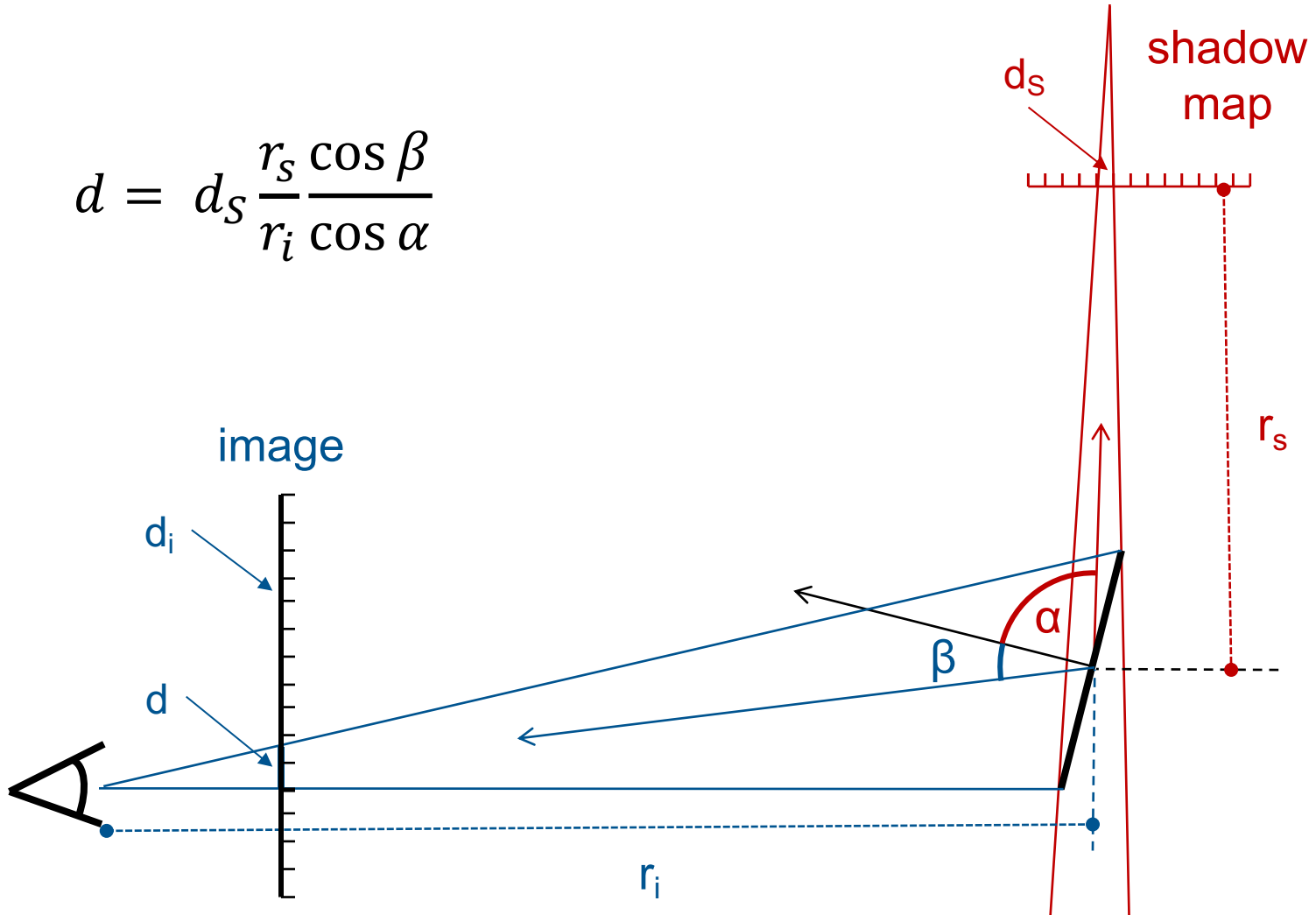
- **Types of Aliasing**

- Projective aliasing: light ray almost parallel to surface
- Perspective aliasing: perspective shortening of view frustrum



Quantifying Sampling Error

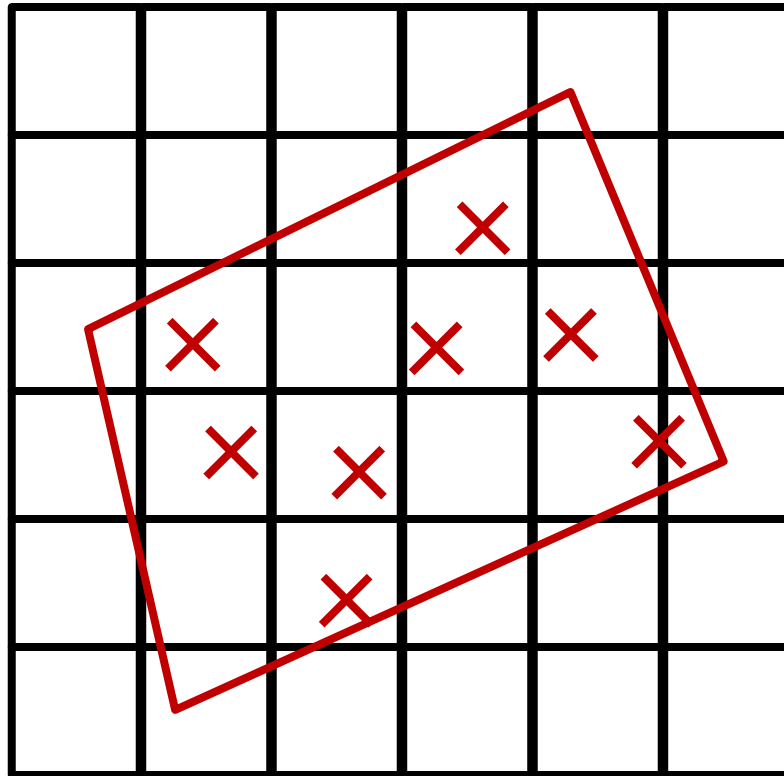
$$d = d_s \frac{r_s \cos \beta}{r_i \cos \alpha}$$



Shadow Map Filtering

- **Percentage-Closer Filtering**

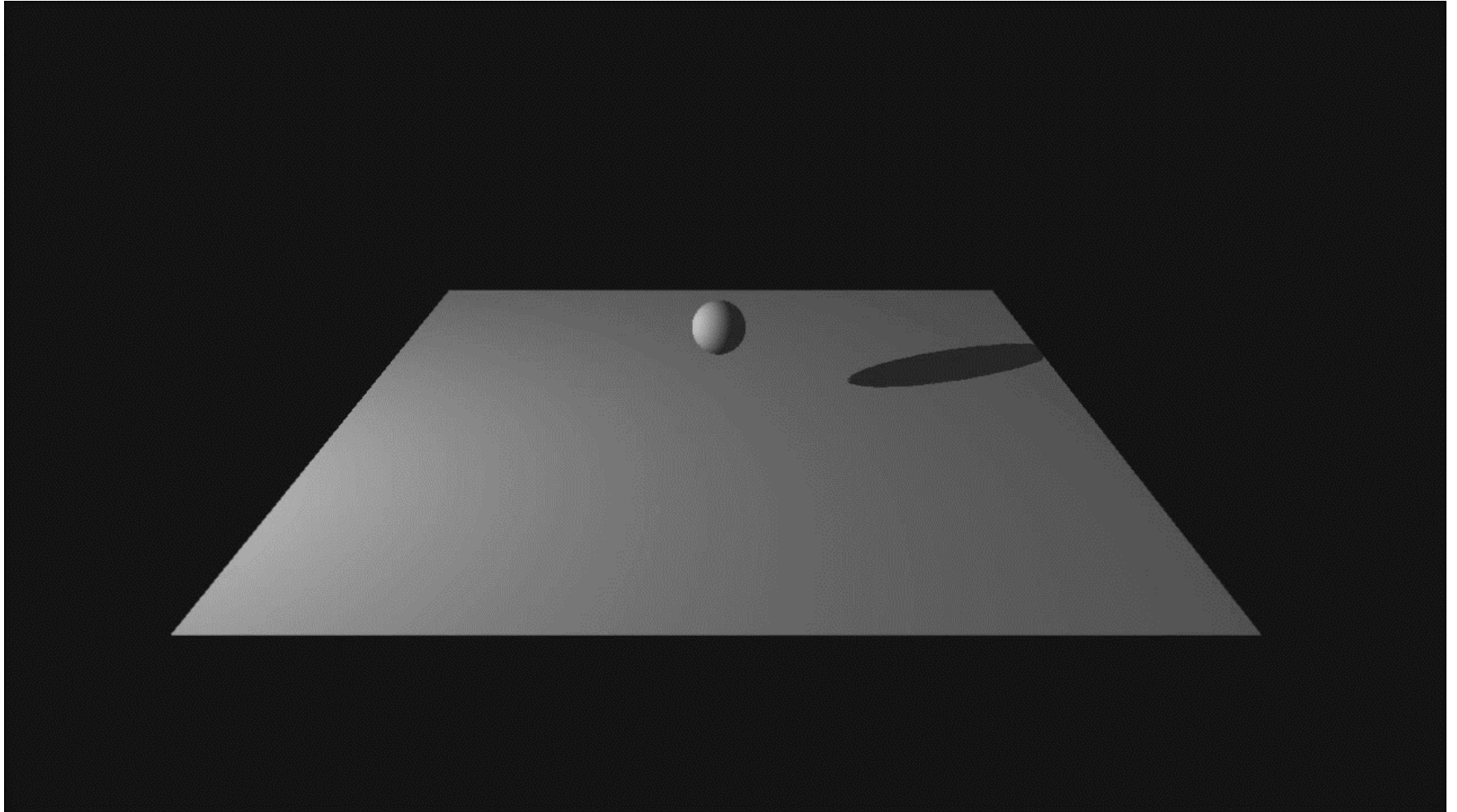
- Map area representing pixel to texture space
- Stochastically sample pixel to find percentage of surface in light



Shadow Map

**Pixel
(in texture space)
possibly enlarged**

Percentage-Closer Filtering



Properties

- **Pro**

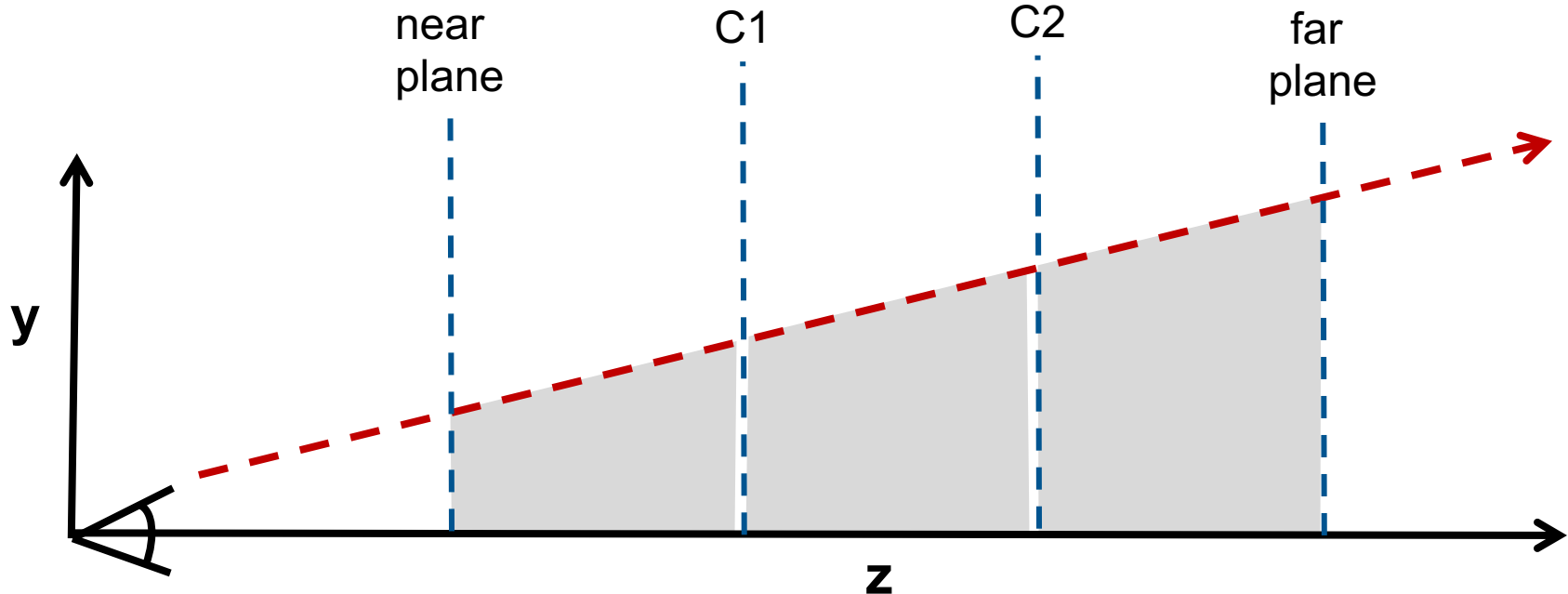
- Display undersampled data in shadow map in a less disturbing way
- Fools our perception: Blurring easily mistaken for penumbra in many situations

- **Con**

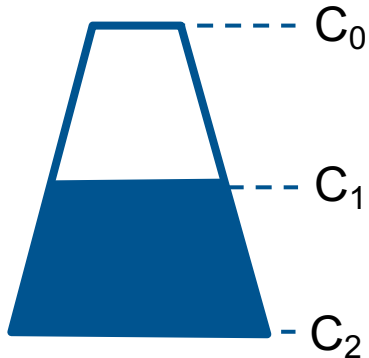
- Not geometrically correct soft shadows with penumbra, just blurred, undersampled shadow map
 - Computationally more expensive than normal shadow maps
- expensive

Parallel Split Shadow Maps (PSSM)

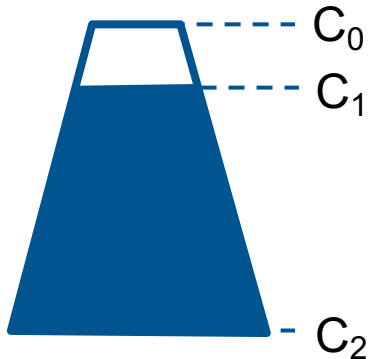
- **Shadow map reparametrization**
 - Optimize distribution of shadow map texels
- **Idea of PSSM: Split depth range**
 - Use different shadow map for every layer



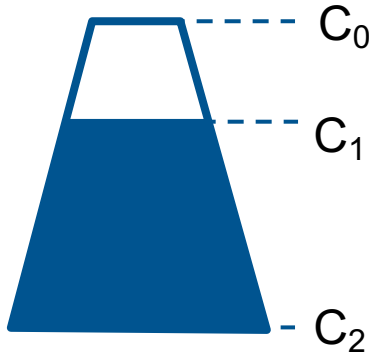
Split Plane Positioning



$$C_i^{uniform} = n + \frac{(f - n)i}{m}$$



$$C_i^{log} = n \left(\frac{f}{n} \right)^{\frac{i}{m}}$$



$$C_i = \frac{C_i^{log} + C_i^{uniform}}{2}$$

Properties

- **Pro**
 - All advantages of shadow maps
 - $n=3$ or 4 mostly solves issues with perspective shadow map aliasing
- **Con**
 - Projective aliasing remains a problem
- **Performance**
 - n additional render pass per light source (but can use multiple render targets)
 - n times memory consumption for shadow maps (but can compensate by reducing resolution due to better usage)

Further Reading

Perspective Shadow Maps:

Marc Stamminger and George Drettakis, *Perspective Shadow Maps*, Proceedings of SIGGRAPH 2002, pp. 557-562

Volumetric Objects:

Tom Lokovic and Eric Veach „*Deep Shadow Maps*“, Proceedings of SIGGRAPH 2000, pp. 385-392

HYBRID RENDERING

Hybrid Rendering Techniques

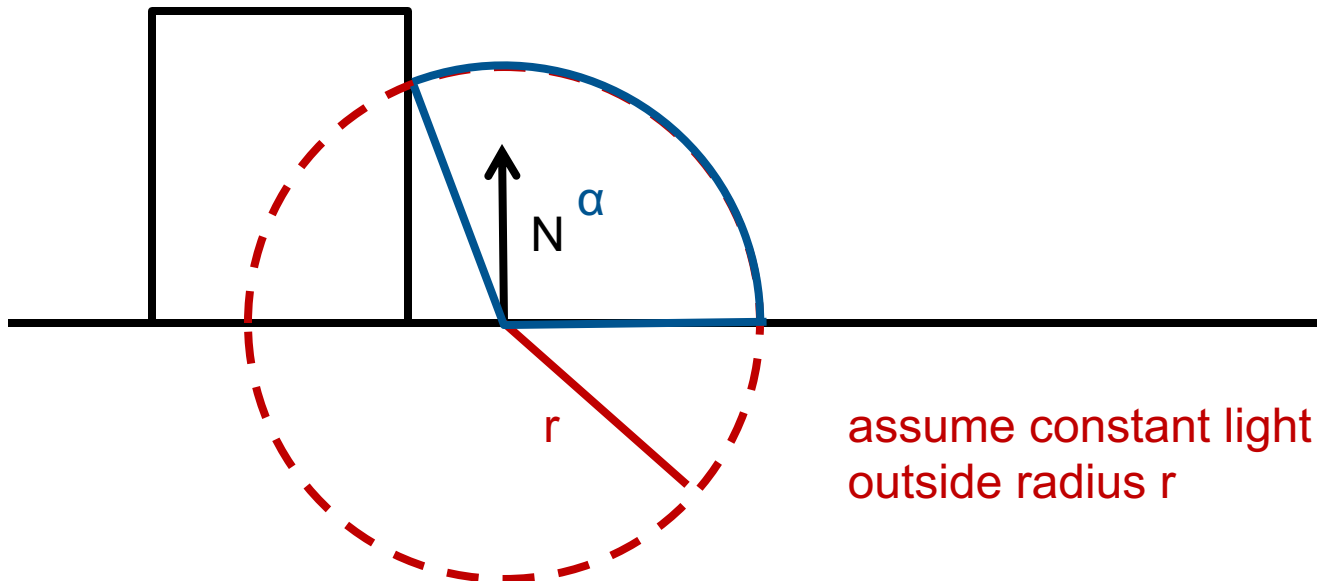
- **Rasterization for primary rendering**
 - Efficiently maps to hardware
 - Resolve visibility using z-buffer
- **Ray-tracing for lighting computation**
 - Ray-scene intersection often too slow for real-time applications
 - Particularly true when sampling large area lights or large opening angles (=many rays per pixel are needed for soft shadows)
- **Core idea**
 - Approximate large number of ray-scene intersections by a small number (often one) cone-scene intersections
 - Intersect against approximate representation of scene that allows fast cone intersection
 - Sufficiently accurate for many lighting purposes

Overview of Techniques

- **Screen Space Ambient Occlusion**
 - Consider z-buffer as a surface that approximates the scene
 - Use ray-tracing in the z-buffer to determine ambient occlusion
- **Sparse Voxel Octree Cone Tracing**
 - Convert entire scene to a view-dependent sparse voxel representation
 - Build mip-map like pyramid over the voxel structure
 - Use „diagonal ray-tracing“ in the voxel pyramid to approximate cone-scene intersection
- **Distance Field Ray Traced Shadows**
 - Build view-dependent voxelized scene representation where voxel contains the distance to the nearest mesh
 - Can be used as acceleration structure for approximate ray-tracing
 - Can be used to calculate ambient occlusion

Ambient Occlusion

- **Calculates shadows against assumed constant ambient illumination**
 - Idea: in most environments, multiple light bounces lead to a very smooth component in the overall illumination
 - For this component, incident light on a point is proportional to the part of the environment (opening angle) visible from the point
 - Describes well contact shadows, dark corners

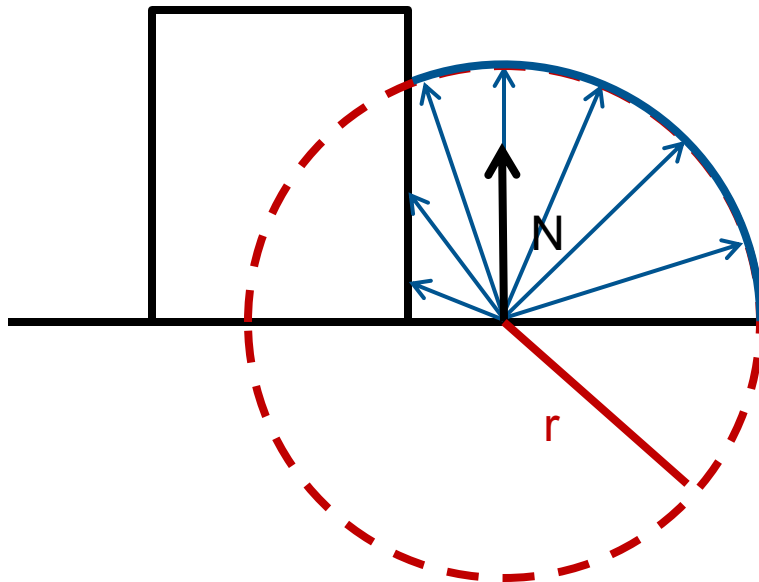


Ambient Occlusion



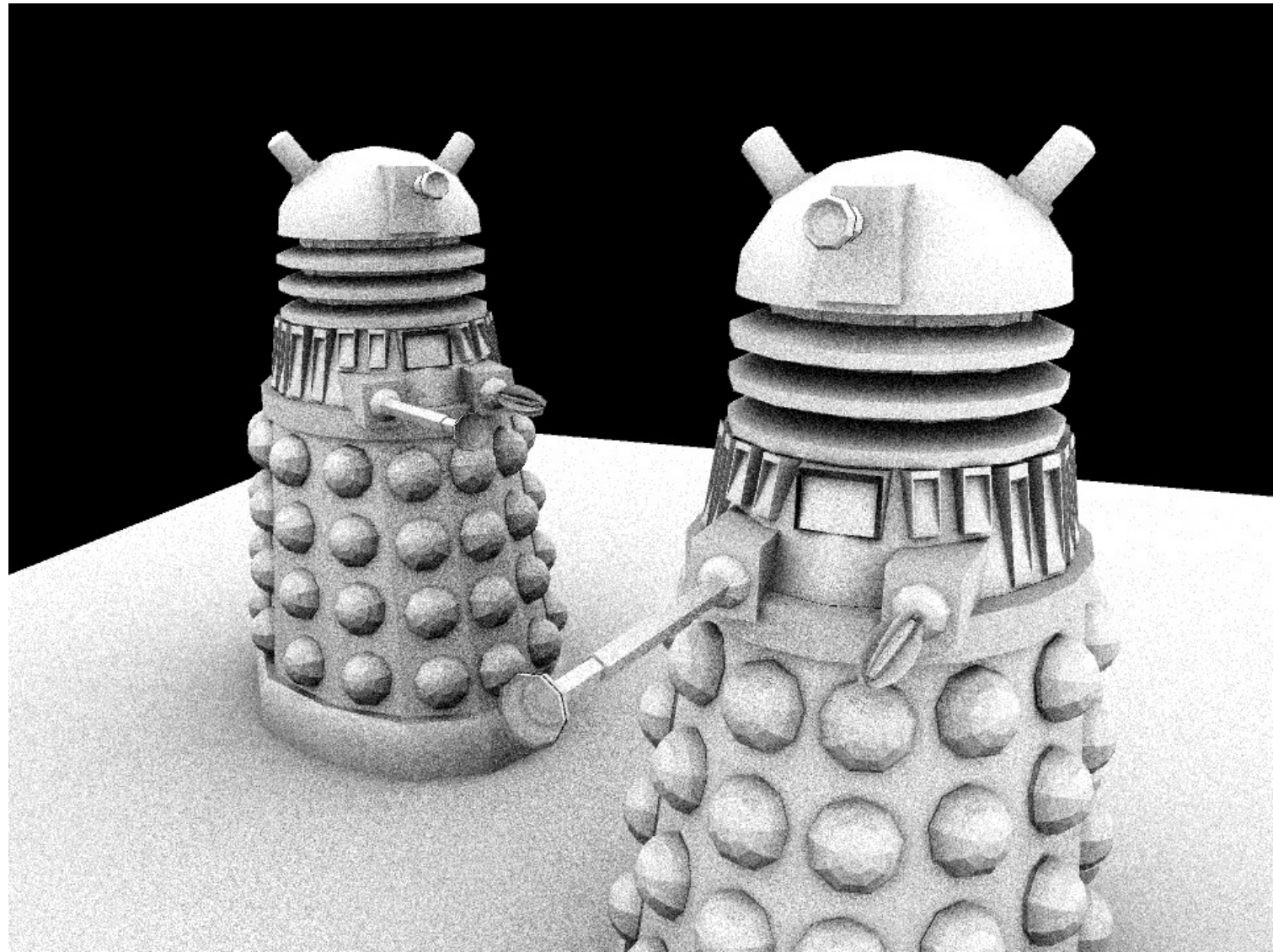
AO Using Ray-Tracing

- **Computation using Ray-Tracing straight forward**
 - Start at point P
 - Sample N directions (D_1 - D_N) from upper hemisphere
 - Shoot shadow rays from P to D_i with maximum length r
 - Count how many rays reach the environment
 - Gives correct result in the limit, but requires many rays to avoid noise (i.e., slow)



assume constant light
outside radius r

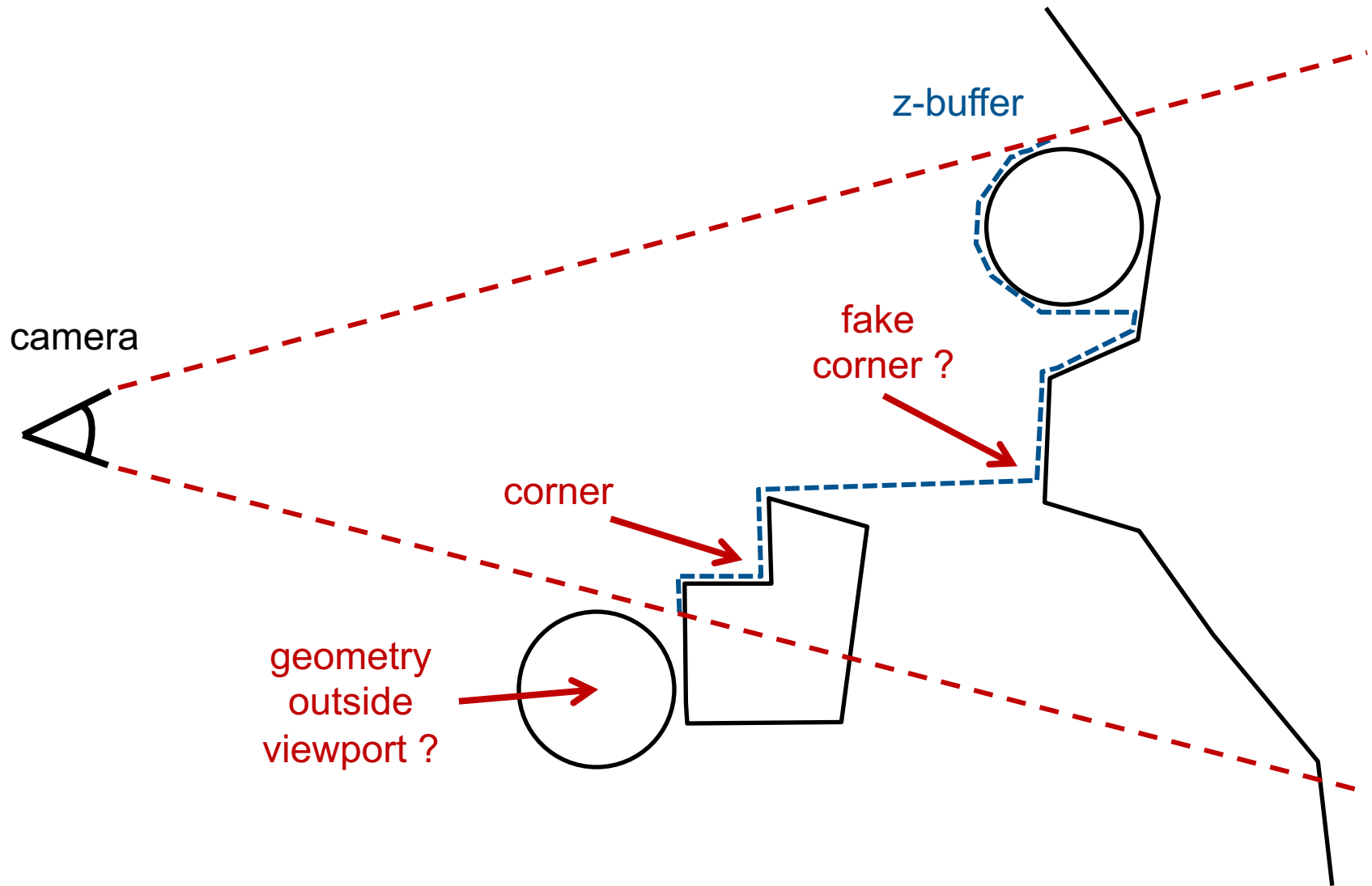
AO Using Ray-Tracing



Screen Space Ambient Occlusion

- **Can we approximate ambient occlusion in real-time?**
 - **Ray-scene intersection too slow**
 - **Idea: Use z-buffer as scene approximation**
 - Horizontal and vertical position give position of point in x,y-direction (camera space)
 - Z-buffer content gives position of point in z-direction (camera space)
 - Contains discrete representation of all visible geometry
 - Use ray-tracing against this simplified scene
-

Screen Space Ambient Occlusion



Properties

- **Pro**

- Allows approximate computation of ambient occlusion in real-time on consumer hardware
- Replaced „ambient term“ of Phong model in most real-time applications (practically highly relevant)

- **Con**

- Relies on scene approximation that may generate artifacts

Further Reading

Tobias Ritschel, Thorsten Grosch, Hans-Peter Seidel,
“Approximating Dynamic Global Illumination in Image Space”, ACM SIGGRAPH Symposium on Interactive 3D Graphics and Games 2009

Louis Bavoil, Miguel Sainz and Rouslan Dimitrov, „Image-Space Horizon-Based Ambient Occlusion“,
Presentation at SIGGRAPH 2008

Louis Bavoil, Miguel Sainz, *“Multi-Layer Dual-Resolution Screen-Space Ambient Occlusion”*, Presentation at SIGGRAPH 2009

Recap

- **Today**

- Re-visited shadows from a rasterization perspective
- Shadow volumes
- Shadow maps, parallel split shadow maps
- Screen space ambient occlusion

- **Next Lecture**

- Sparse Voxel Octree Cone Tracing
 - Distance Field Ray Traced Shadows
-